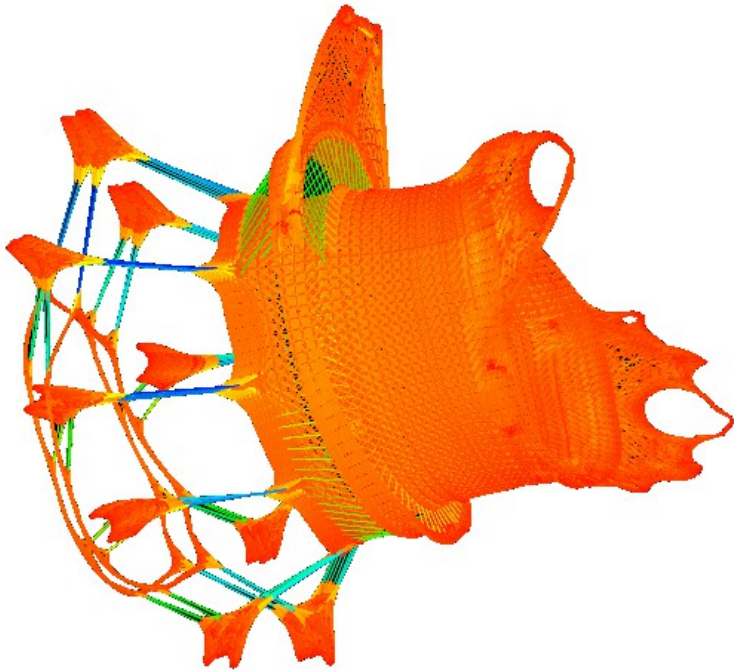


# SYSC5906 - Directed Studies (Distributed Sparse Matrices)

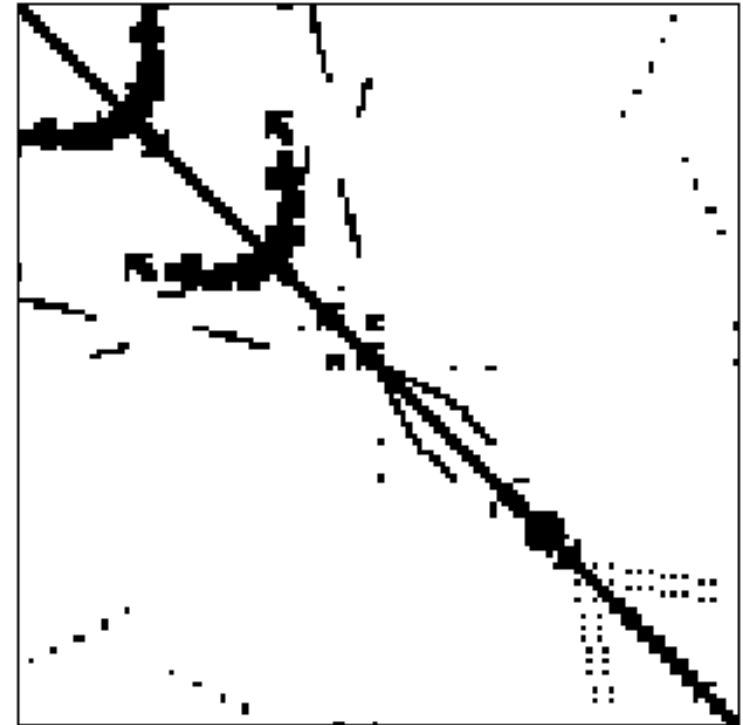
A Report

Alistair Boyle 2010

# Overview



Storage  
Solution  
Ordering  
Distribution



[<http://www.cise.ufl.edu/research/sparse/matrices/Rothberg/gearbox.html>, 107624 nodes, 3250488 edges, UF Sparse Matrix Collection]

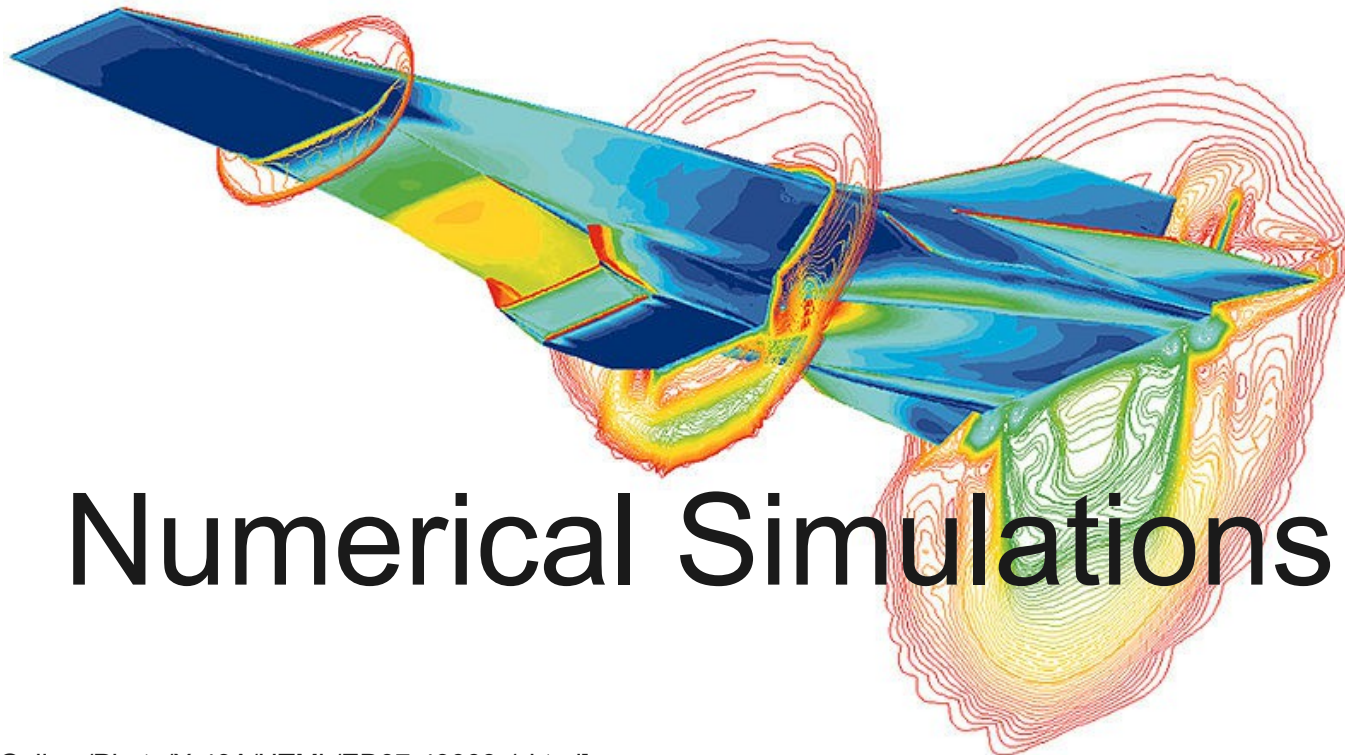


<http://creativecommons.org/licenses/by-nc-sa/3.0/>

Title image: <http://www.flickr.com/photos/8702301@N06/5006243147/>

# Motivation

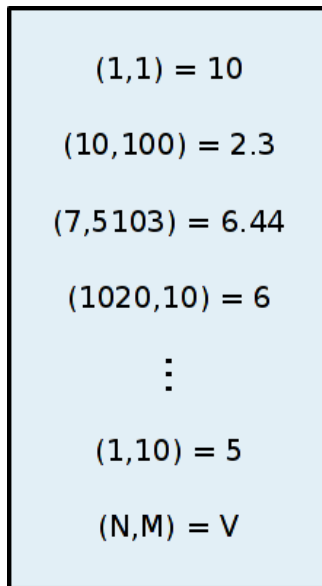
- Linear Equations
  - Exact solutions
  - Approximations
- Eigenvalues/vectors
  - Vibration
  - Harmonics



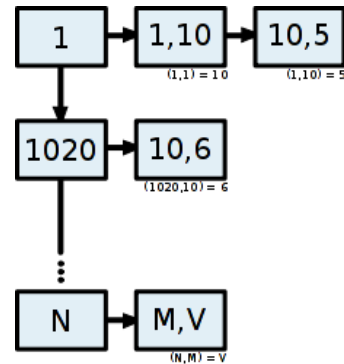
## Numerical Simulations

# Sparse Storage

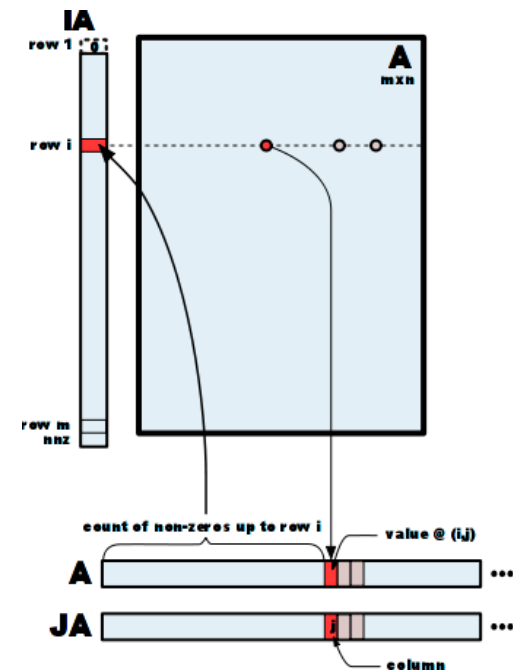
## Triplets



## List-of-Lists

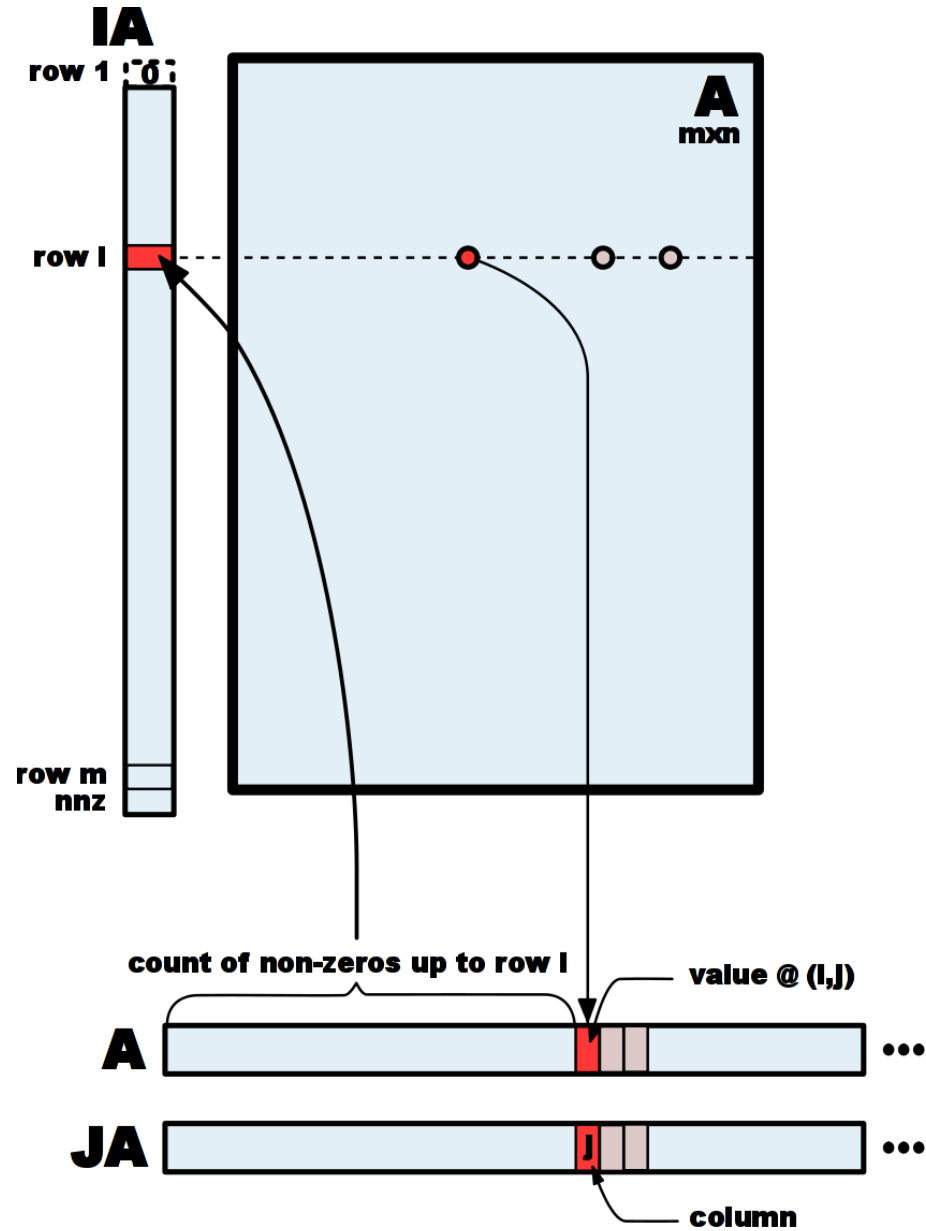


## CSR



# Sparse Storage

## Compressed Sparse Row format

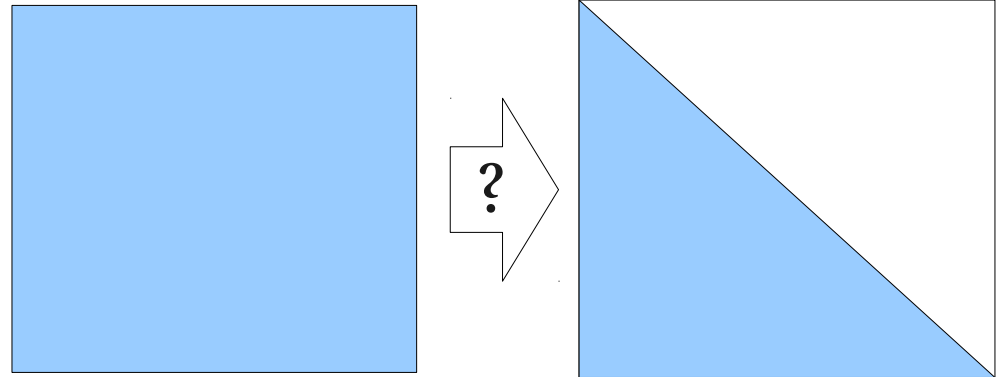


# Sparse Storage File Formats

- Matrix Market
  - Triplets format, ASCII
- Harwell-Boeing
  - Compressed Sparse Column (CSC) format storage
  - Assembled, elemental, real, complex, pattern matrices
  - Support for multiple right-hand sides, guesses, solutions
- Rutherford-Boeing
  - An updated version of the Harwell-Boeing format
  - Supplementary matrix information
    - Orderings, estimates, partitions, Laplacian values, geometry, etc.

# Solution Decompositions

Involves  
converting  
matrices to  
triangular or  
diagonal form  
through matrix  
transformations



# Solution

## LU Decomposition

- If  $A$  is square:

$$Ax = b \Rightarrow x?$$

$$A = LU$$

$$Ly = b \Rightarrow y$$

$$Ux = y \Rightarrow x$$

1. decomposition  
(Crout or Doolittle algorithms)

2. forward substitution

3. backward substitution

- $L$  is unit lower triangular,  $U$  is upper triangular



# Solution

## Cholesky Decomposition

- If  $A$  is square, hermitian, positive definite:

$$Ax = b \Rightarrow x?$$

$$A = LL^H$$

$$Ly = b \Rightarrow y$$

$$L^H x = y \Rightarrow x$$

1. decomposition

(Choleksy-Crout/Banachiewicz algorithms)

2. forward substitution

3. backward substitution

- Special case of LU decomposition where  $U = L^H$

# Solution

## QR Decomposition

- If  $A$  is square, nonsingular:

$$\operatorname{argmin} \|Ax - b\|_2^2 \Rightarrow x? \quad (\text{Least squares solution})$$

1. decomposition (Gram-Schmidt, Givens, Householder algorithms)

$$A = QR \Rightarrow Q^H A = Q^H Q R = R$$

$$\|Q^H Ax - Q^H b\|_2^2 = \left\| \begin{array}{c} Rx - c_1 \\ -c_2 \end{array} \right\|_2^2 \quad \dots \quad c = Q^H b, Rx = c_1 \Rightarrow x$$

- $Q$  is orthogonal/unitary,  $R$  is upper triangular

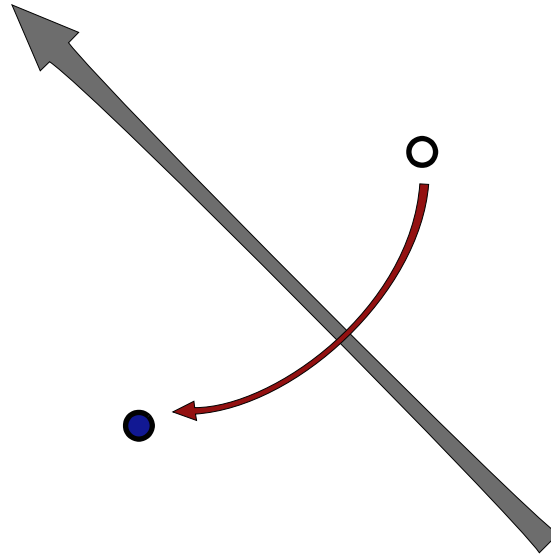
$$Q^H Q = I, Q^{-1} = Q^H$$

# Solution

## Other Decompositions

Eigenproblems: Schur factorization  
Singular Value Decompositions

# Solution: QR factorization Givens Rotations



- Rotation of a point about a line

# Solution: QR factorization Givens Rotations

$$\begin{bmatrix} a & b \\ -b & a \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} m \\ 0 \end{bmatrix}$$

$$m = \sqrt{x^2 + y^2}$$

$$a = x/r$$

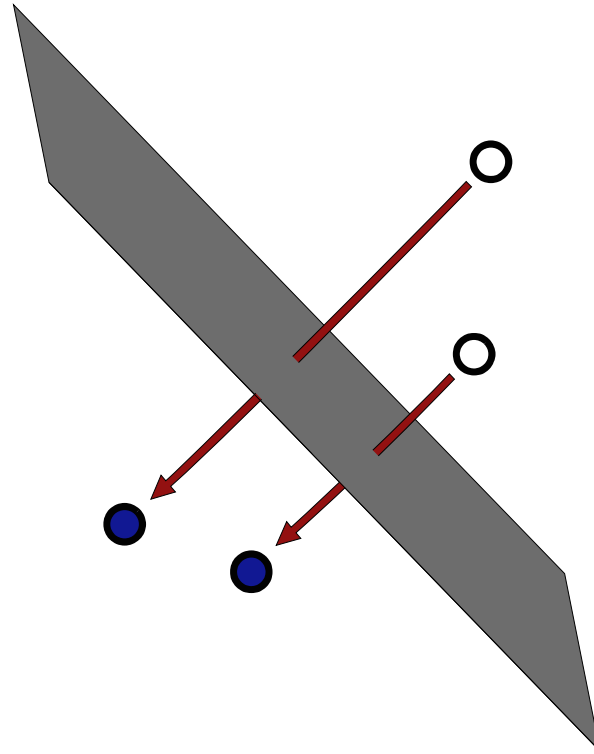
$$b = y/r$$

Example

$$G_n = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & a & 0 & b & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & -b & 0 & a & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Only four entries in the transformed matrix are modified for a single Givens rotation. Result is one entry in the transformed matrix becoming zero.

# Solution: QR factorization Householder Reflections



- Reflection of points across a hyper-plane

# Solution: QR factorization Householder Reflections

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & a_{22} & \dots \\ a_{31} & a_{32} & \dots \end{bmatrix} \quad \longrightarrow \quad A' = Q A = \begin{bmatrix} \alpha & a_{12}' & \dots \\ 0 & \boxed{a_{22} \dots} \\ 0 & \boxed{a_{32} \dots} \end{bmatrix}$$

$$\alpha = \|x\|, \quad x = [a_{11} \ a_{21} \ a_{31}]^T$$

$$e_1 = [1 \ 0 \ 0 \ \dots]^T$$

$$u = x - \alpha e_1$$

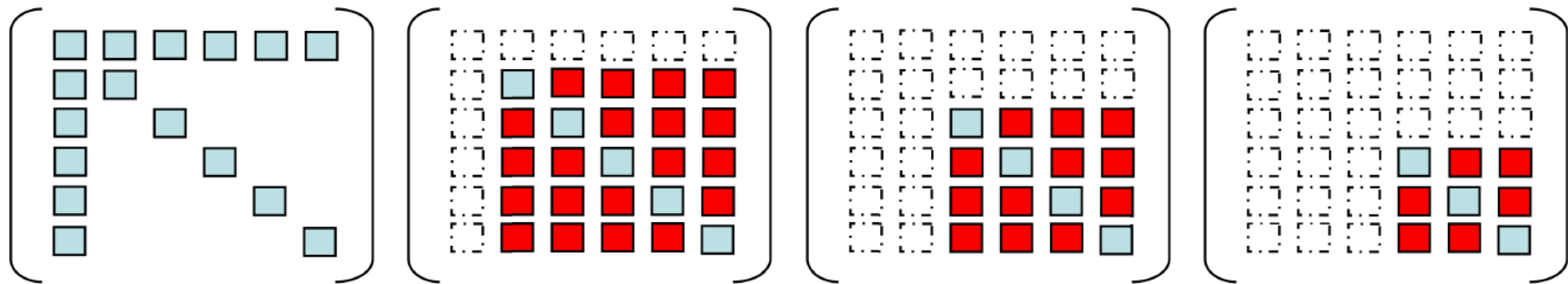
$$v = u / \|u\|$$

$$Q = I - 2 v v^T$$

Removes column at-a-time. Operates on submatrices as upper triangular matrix is produced.

# Fill-in

- As a matrix is decomposed, it may fill-in: previously zero entries become non-zero, making more work for the later stages.

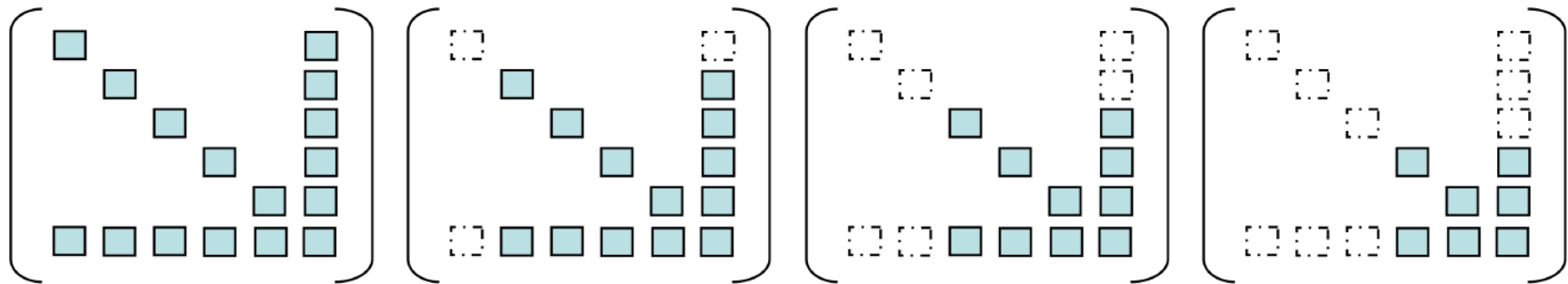


First 4 steps in Cholesky algorithm  
Blue: initially non-zero,  
Red: fill-in



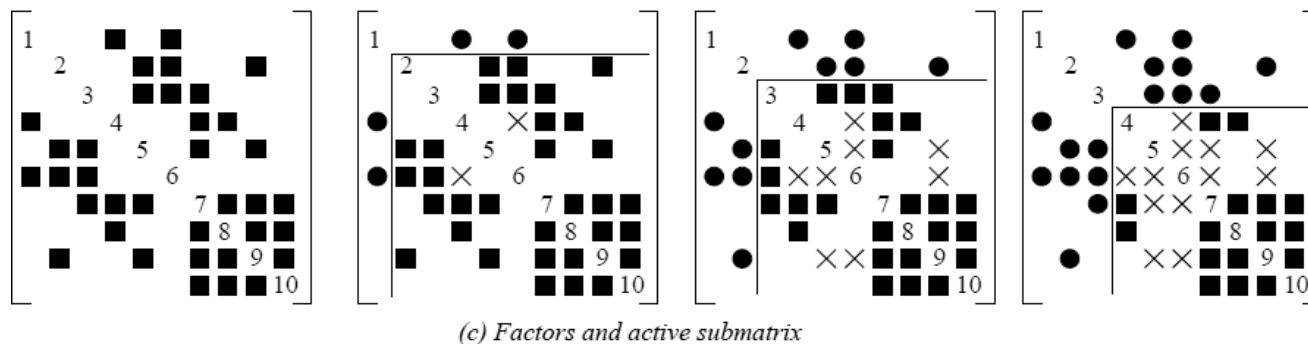
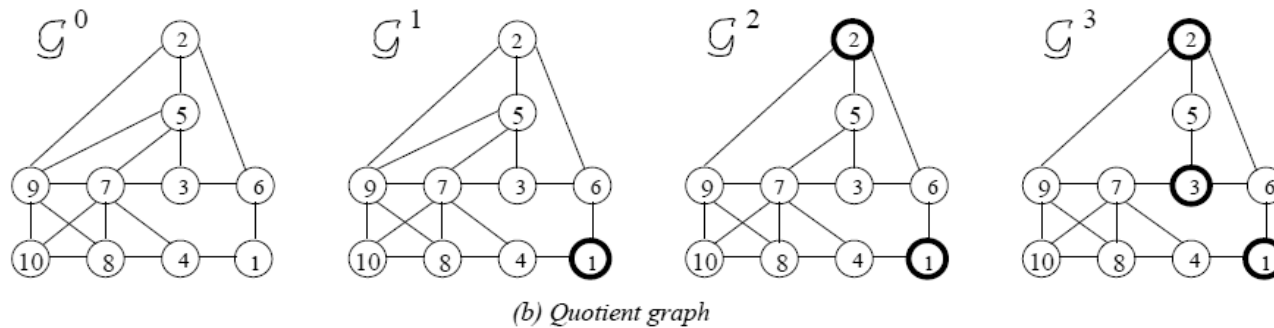
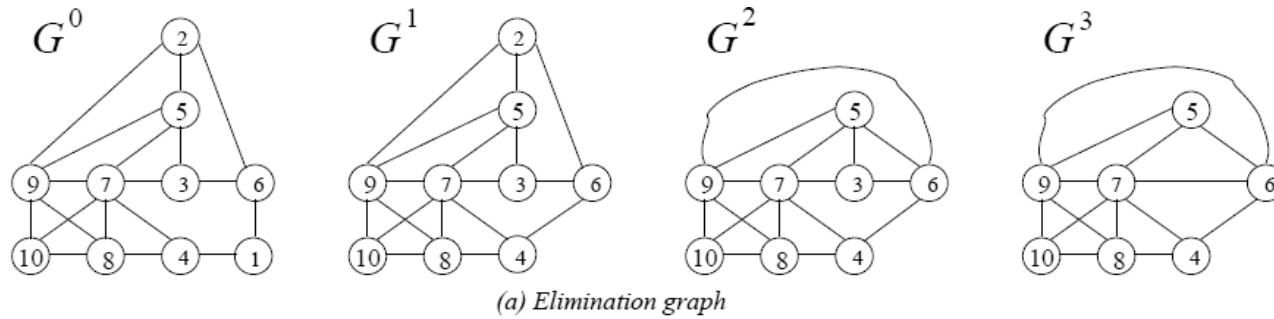
# Fill-in

- Reordering the first row & column: massive improvement in required operations
- But... finding a “good” ordering is NP-hard



Reordered, First 4 steps in Cholesky algorithm  
Blue: initially non-zero,  
Red: fill-in (none)

# Ordering Minimum Degree



# Orderings

## Nested Dissection

- Divide and Conquer
  - Recursively split based on mutual independence

$$A = \begin{bmatrix} a_{11} & a_{12} & 0 \\ a_{21} & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{bmatrix} \quad \longrightarrow \quad A' = \begin{bmatrix} a_{11} & 0 & a_{13}' \\ 0 & a_{33} & a_{23}' \\ a_{31}' & a_{32}' & a_{33}' \end{bmatrix}$$

# Ordering

- MD, MMD, AMD
- PORD
- UMFPACK

## Hybrid

- METIS
- SCOTCH

# Ordering parallel ordering

ParMETIS  
pt-SCOTCH

Hybrid  
minimum degree  
nested-dissection

[ ParMETIS - <http://glaros.dtc.umn.edu/gkhome/metis/parmetis/overview>]

[ ptSCOTCH - <http://www.labri.fr/perso/pelegrin/scotch/> ]

# Distribution

## Left-Looking

- Two operations
  - Divide column by sqrt of its diagonal
  - Add a multiple of one column to another
- Column-based
  - iterates on columns to the left of the current column
- Save updates until a column is completed

# Distribution

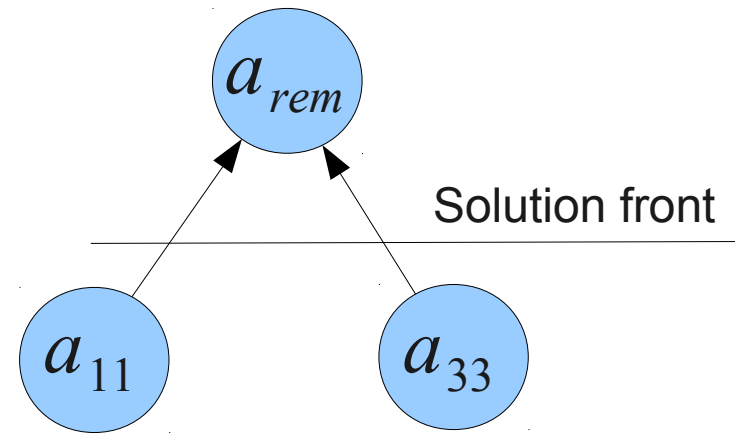
## Right-Looking

- Two operations
  - Divide column by sqrt of its diagonal
  - Add a multiple of one column to another
- “Submatrix”-based
  - Iterates on columns to the right of the current column
- Requires (inexpensive) search on destination's storage to find new non-zero locations to insert

# Distribution

## Multifrontal (Right-Looking)

$$A' = \begin{bmatrix} a_{11} & 0 & a_{13}' \\ 0 & a_{33} & a_{23}' \\ a_{31}' & a_{32}' & a_{33}' \end{bmatrix}$$



Form a tree and solve independent portions.

Updates to the matrix occur at the “front”.















Updates are kept on a stack – typically +25% space.

Can have multiple independent fronts in parallel.




Can take advantage of “super-nodes”

















# Solving in Serial

- CHOLMOD 
- MA57 
- MA41 
- MA42 
- MA67 
- MA48 
- Oblio 
- SPARSE 
- SPARSPAK  
- SPOOLES 
- SuperLLT 
- SuperLU 
- UMFPACK 

## Legend




-  symmetric positive definite
-  symmetric
-  non-symmetric

# Solving in Parallel shared memory













- BCSLIB-EXT  
- Cholesky 
- DMF 
- MA41 
- MA49
- PanelLLT 
- PARASPAR 
- PARADISO 
- SPOOLES 
- SuiteSparseQR
- SuperLU\_MT 
- TAUCS  
- WSMP  

## Legend

---




-  symmetric positive definite
-  symmetric
-  non-symmetric

# Solving in Parallel distributed

- DMF 
- DSCPACK 
- MUMPS   
- PaStiX 
- PSPASES 
- SPOOLES 
- SuperLU\_DIST 
- S+ 
- WSMP  

## Legend

---

-  symmetric positive definite
-  symmetric
-  non-symmetric

# Questions?

