# Slope Stability Monitoring

## through Impedance Imaging

Alistair Boyle, Paul Wilkinson, Jonathan Chambers, Nolwenn Lesparre, Andy Adler a collaboration between







Spain 1998: Los Frailes Tailings Dam, Minas de Aznalcóllar 1.5M m<sup>3</sup> tailings solids + 5.5M m<sup>3</sup> acidic tailings water

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Image: http://www.cerm3.mining.ubc.ca/Images/LosFrailes.jpg

### Provost, AB, Canada (2013) CP Rail freight train; 17 potash cars derailed, ~100m track destroyed.

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THROUGH IMPEDANCE IMAGING Image & report: http://www.tsb.gc.ca/eng/rapports-reports/rail/2013/r13e0069/r13e0069.asp

#### Slope Stability can represent



#### an environmental risk

effective mitigation: a monetary benefit

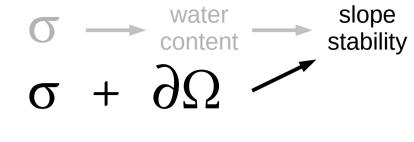
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### **PREDICTIVE: (?)**

1) conductivity  $\sigma$  – water content:

- Archie's Law (sandstone)
- Waxman-Smits Equation (clay)
- 2) water content slope stability:
  - Static Slope Stability Analysis based on soil types and water content



**Direct Monitoring**:

1) Direct movement estimate from reconstruction

- Online, remote monitoring
- Cost effective equipment vs. Laser range finding

Slope Stability Monitoring through Impedance Imaging

## A TEST SITE Hollin Hill, UK: A Slow Moving Landslide



[Paul Wilkinson et al.,"Geoelectrical Landslide Tracking", EAGE2010]

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## Absolute Solution Measurements & Reconstruction

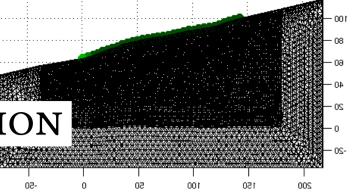
- 32 electrode, linear array, downslope
- Initial & final electrode positions & slope profile from RTK GPS

1) uniform initial  $\sigma$  est. based on best-fit, also used as fixed background  $\sigma$ 

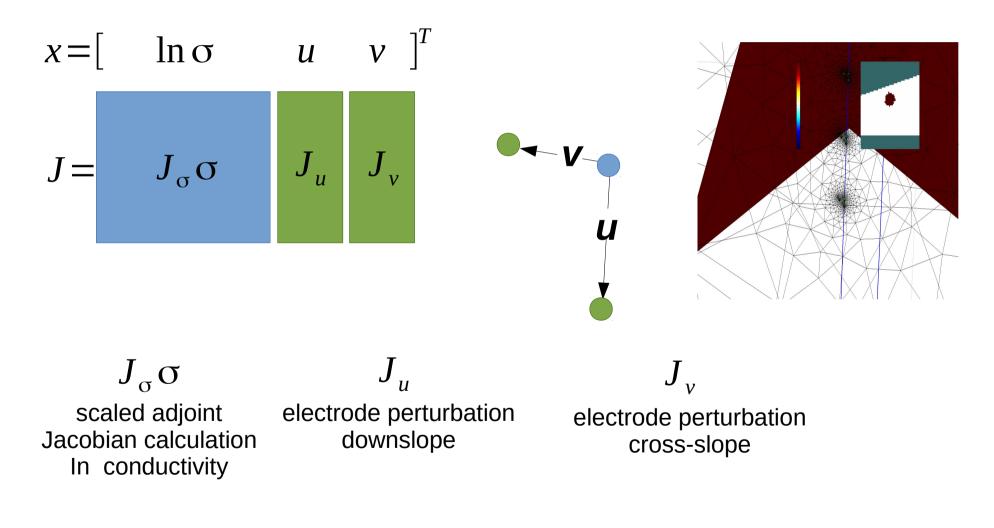
2) apparent resistivity = measurements scaled for geometry and stimulus
• improved numeric stability by normalizing magnitudes

3) log  $\sigma$ : conductivity Jacobian (negativity constraint)  $J_{\ln\sigma} = \partial \sigma = \frac{\partial b}{\partial \ln \sigma} = \frac{\partial b}{\partial \sigma} \frac{\partial \sigma}{\partial \ln \sigma} = \frac{\partial b}{\partial \sigma} \sigma = J_{\sigma} \sigma$ 4) movement Jacobian by perturbation; alternate electrode sites in model 5) 2.5D: fine 3D fwd model, coarse 2D inv model, fitted to electrode pos. 6) absolute iterative Gauss-Newton solution

RTK: Real Time Kinematic; a differential GPS technology (± 1 - 4 cm absolute, 5mm relative to base station) APRIL 2014 SLOPE STABILITY MONITORING THROUGH IMPEDANCE IMAGING



## Absolute Solution Jacobian & Regularization Terms



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## Absolute Solution Forward Solver Time

 Movement perturbation is computationally slow (a fine mesh), one forward solution per Gauss-Newton iteration

$$P_M = N_{el} D_{DoF} P_{orig}$$

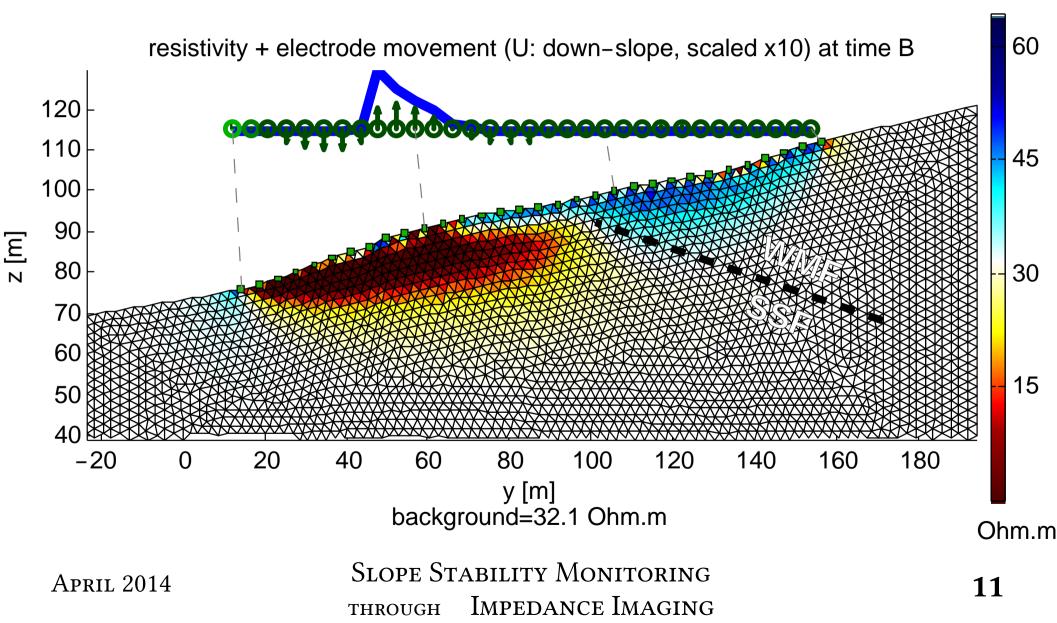
 $N_{el}$ =32,  $D_{DoF}$ =2,  $P_M$   $\approx$  37000

- Developed a generalized stim/meas improvement routine that rearranges stimulus and measurements to minimize matrix operations, skip redundant results, providing a transparent (to the user) optimization.
- Forward solution in 45 minutes becomes
   3.75 minutes for rearrangement + 15 seconds per solution
   ... run times were two orders of magnitude faster

Timings on an Intel Xeon 2.6GHz, 8 cores, 64GB memory

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# **Reasonable** Agreement with "Ground Truth"



# DISCUSSION

- Resistivity distribution agrees with geological evidence
- Estimated movement is in reasonable agreement with GPS measurements
- Further Refinement:
  - Regularization and constraints for movement
  - Conjugate Gradient solver versus Gauss-Newton
  - Better iterative solver line search

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## Thank You

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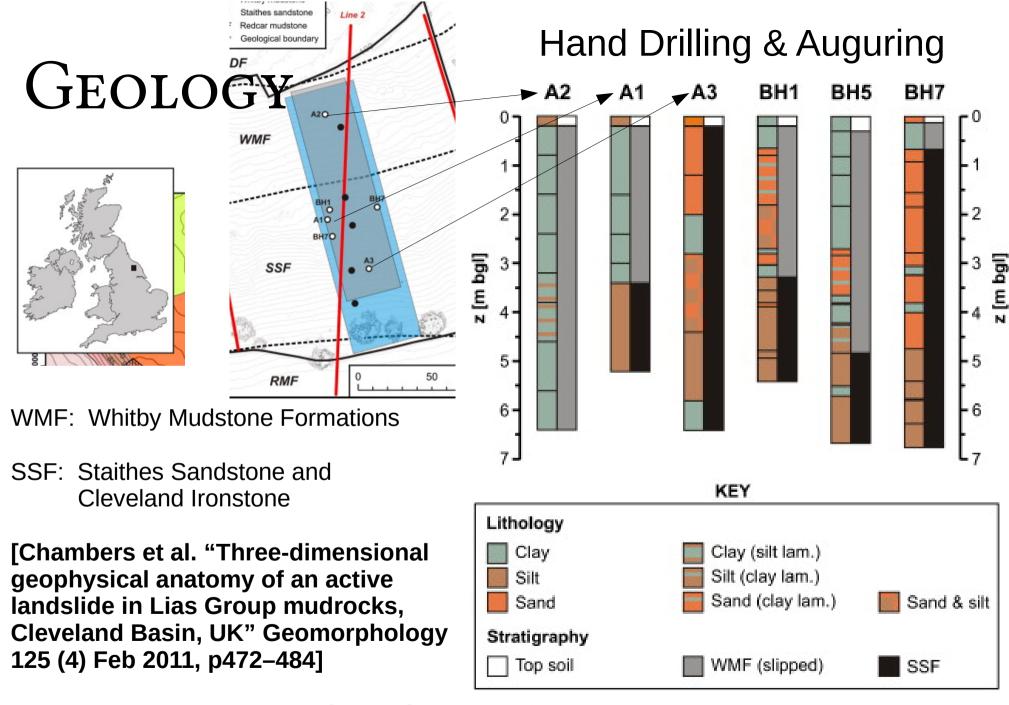






#### Potash – water soluble potassium salts Main use: fertilizer largest producer: CAN worldwide 30M tons/yr

http://en.wikipedia.org/wiki/Potash Image: http://resourcescommittee.house.gov/subcommittees/emr/usgsweb/photogallery/



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