

ESTIMATING ELECTRODE MOVEMENT in Two Dimensions

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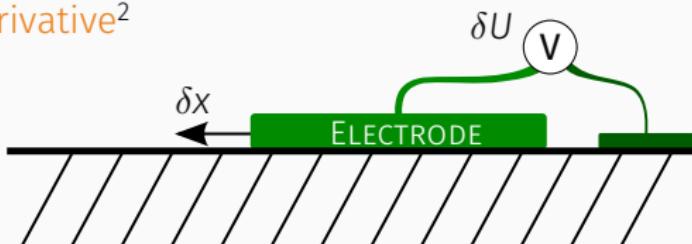
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ELECTRODE MOVEMENT CORRECTIONS

Jacobian Methods $J_{m,x} = \frac{\delta U}{\delta x}$

1. Naïve perturbation
2. **perturbation**
3. rank-one update¹
4. **Fréchet derivative**²



¹Gómez-Laberge C, Adler A. *Physiol Meas* 29(6):S89–S99, 2008

²Dardé J, Hakula H, Hyvönen N, et al. *Inverse Problems and Imaging* 6(3):399–421, 2012

MOTIVATION

- explore sensitivity of the direct perturbation method
- understand Fréchet derivative and build an implementation
- ask the Engineering question:

Do these methods give the same answers for a simplified model?

MOVEMENT JACOBIAN

Movement In our case, two-dimensional tangential electrode movement on a fixed boundary.

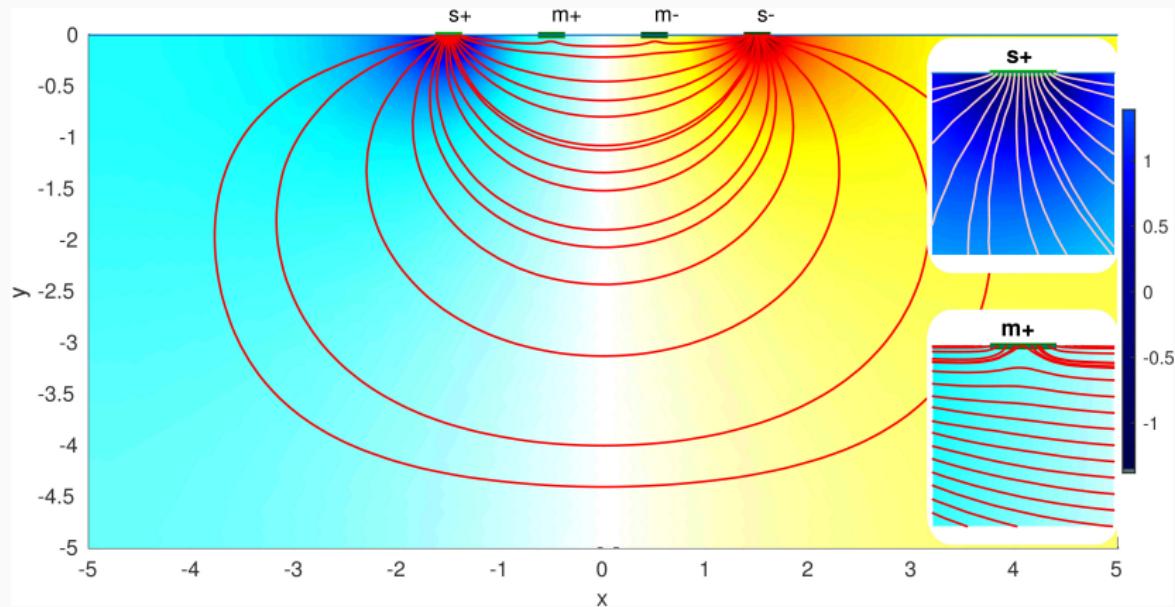
Jacobian An estimate of the local slope.

For Gauss-Newton updates, the Jacobian, in part, determines search direction δx , followed by a line search for distance α . If sufficiently linear, then $\alpha = 1$ can work well.

$$\delta x = (J^T J + \lambda^2 R^T R)^{-1} J^T U \quad (1)$$

$$x_{n+1} = x_n + \alpha \delta x \quad (2)$$

A TWO-DIMENSIONAL HALF-SPACE MODEL



$$h_{max} = 0.1 \text{ m}$$

$$d_{e\ell} = 0.2 \text{ m}$$

$$z_C = 0.02 \Omega \cdot \text{m}$$

$$\sigma = 1 \text{ S/m}$$

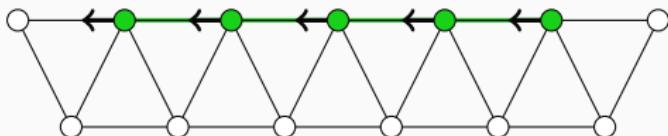
PERTURBATION

Naïve Perturbation

Naïve Perturbation



$$J_m = \frac{\delta U}{\delta x}$$



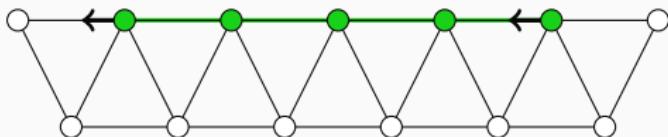
all electrode nodes are perturbed

PERTURBATION

Perturbation

Perturbation

$$J_m = \frac{\delta U}{\delta x}$$



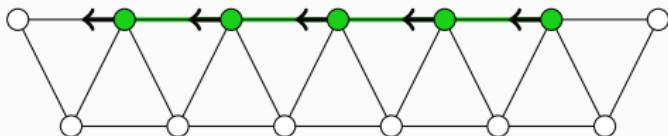
electrode *boundary* nodes are perturbed

Rank-One Update

Gómez-Laberge



$$J_m = \frac{\delta U}{\delta x}$$

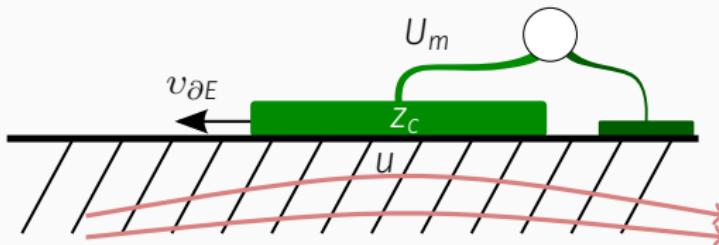


“the discrete form of the Lie derivative of the conductivity tensor”;
the matrix rank-one update to the conductivity Jacobian due to FEM
node movement

accounts for contact impedance z_c effects
in the Complete Electrode Model

$$\delta U = J_m h + O(h^2)$$

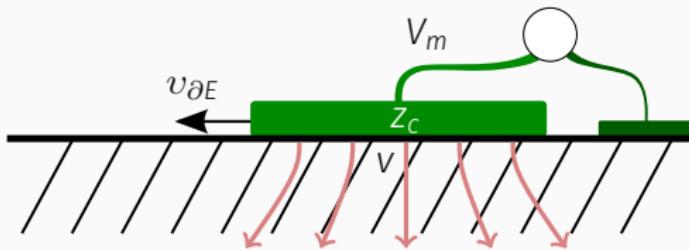
$$J_m \cdot h = \frac{1}{z_c} \int_{\partial E} (h \cdot v_{\partial E})(U_m - u)(V_m - v) ds$$



accounts for contact impedance z_c effects
in the Complete Electrode Model

$$\delta U = J_m h + O(h^2)$$

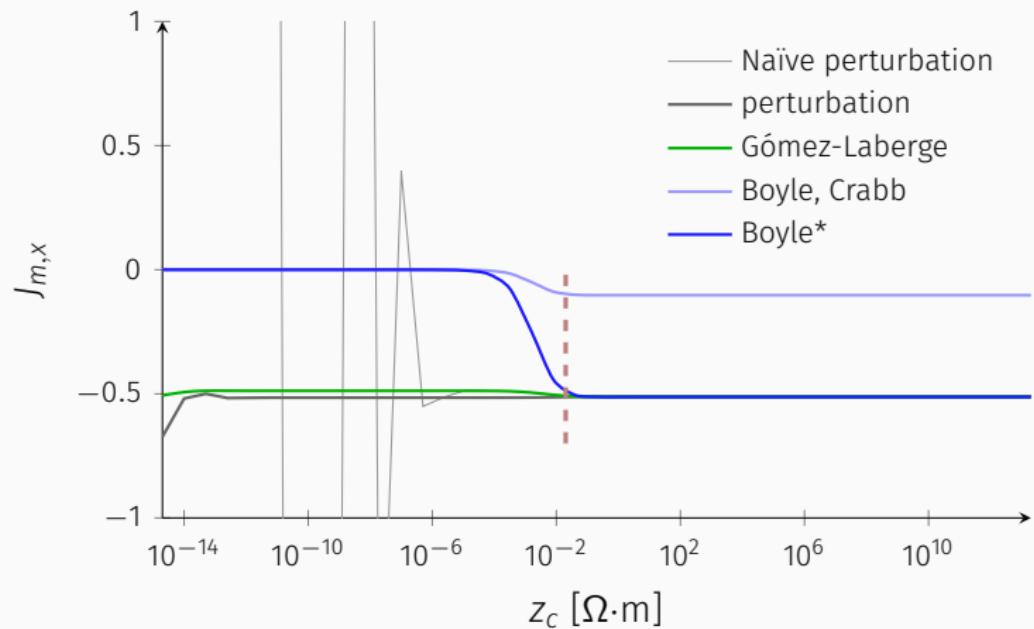
$$J_m \cdot h = \frac{1}{z_c} \int_{\partial E} (h \cdot v_{\partial E})(U_m - u)(V_m - v) ds$$



Boyle* 

*What if the contact impedance z_c units are wrong:
[$\Omega \cdot m$] rather than [Ω]?*

CONTACT IMPEDANCE Z_C FOR THE M+ ELECTRODE

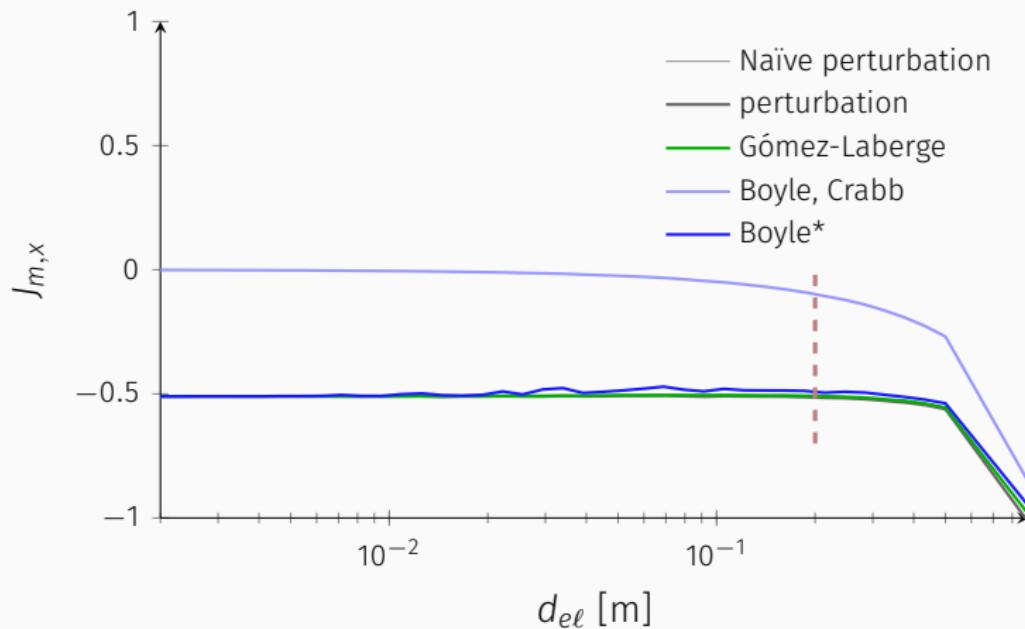


$h_{max} = 0.1$ m

$d_{e\ell} = 0.2$ m

plot for m+

ELECTRODE DIAMETER d_{el} FOR THE M+ ELECTRODE

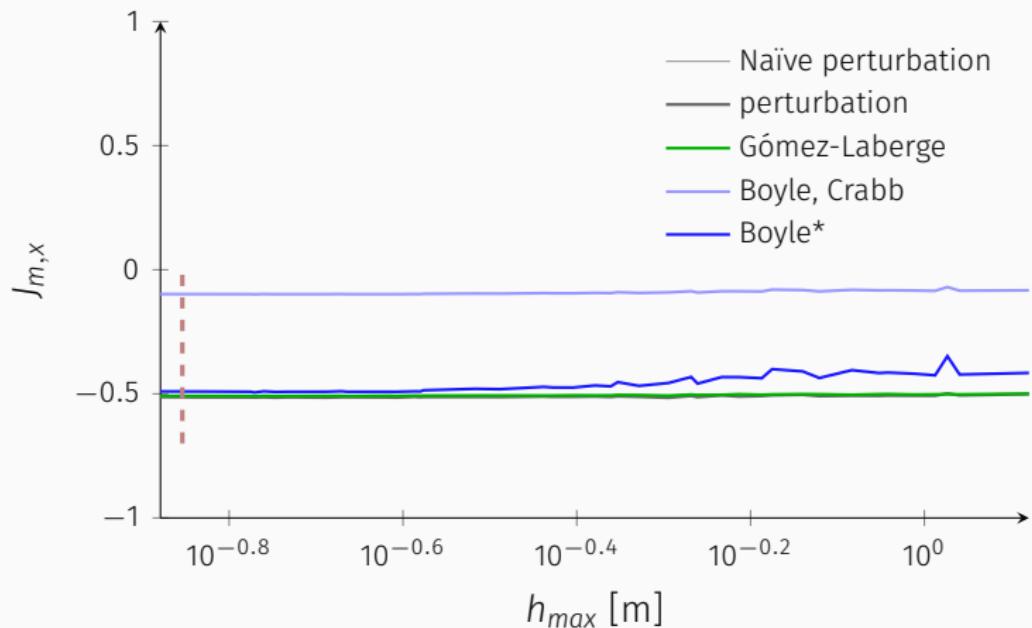


$h_{max} = 0.1$ m

$z_C = 0.02$ $\Omega \cdot \text{m}$

plot for m+

MESH DENSITY h_{max} FOR THE M+ ELECTRODE



$d_{e\ell} = 0.2$ m

$z_C = 0.02$ $\Omega \cdot \text{m}$

plot for m+

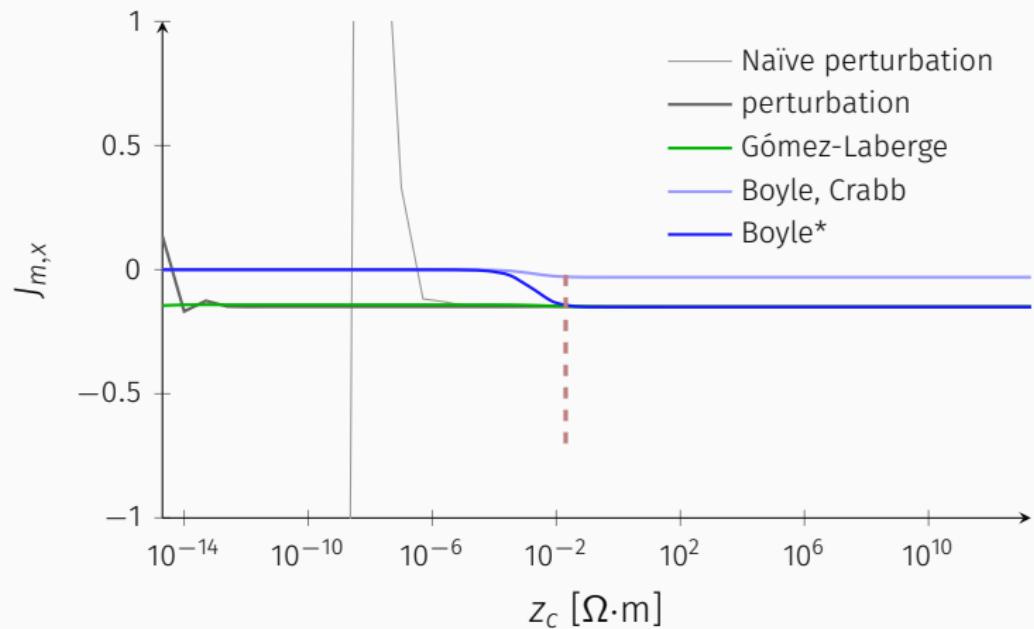
DISCUSSION

What does this mean for movement solutions?

- Fréchet deriv. is **fast**
(forward solutions reused from *adjoint method/conductivity*)
- Fréchet deriv. magnitudes **differ** from perturbation methods
(sign is correct/stable;
hyper-parameter λ and/or line search α values will be different)
(contact impedance units?)
- Fréchet deriv. results **collapse** for small contact impedance
 $z_c \ll \Omega_\sigma$, and more sensitive to mesh density h_{max} than
conductivity solutions
(use “rank-one update” method when necessary?)

QUESTIONS?

CONTACT IMPEDANCE Z_c FOR THE S- ELECTRODE

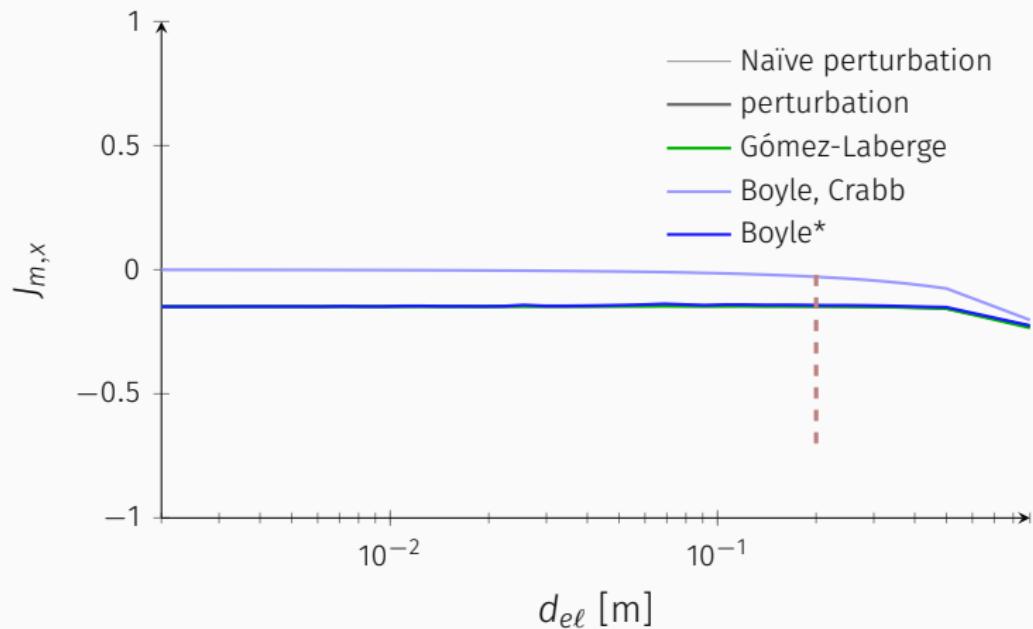


$h_{max} = 0.1$ m

$d_{e\ell} = 0.2$ m

plot for s-

ELECTRODE DIAMETER d_{el} FOR THE S- ELECTRODE

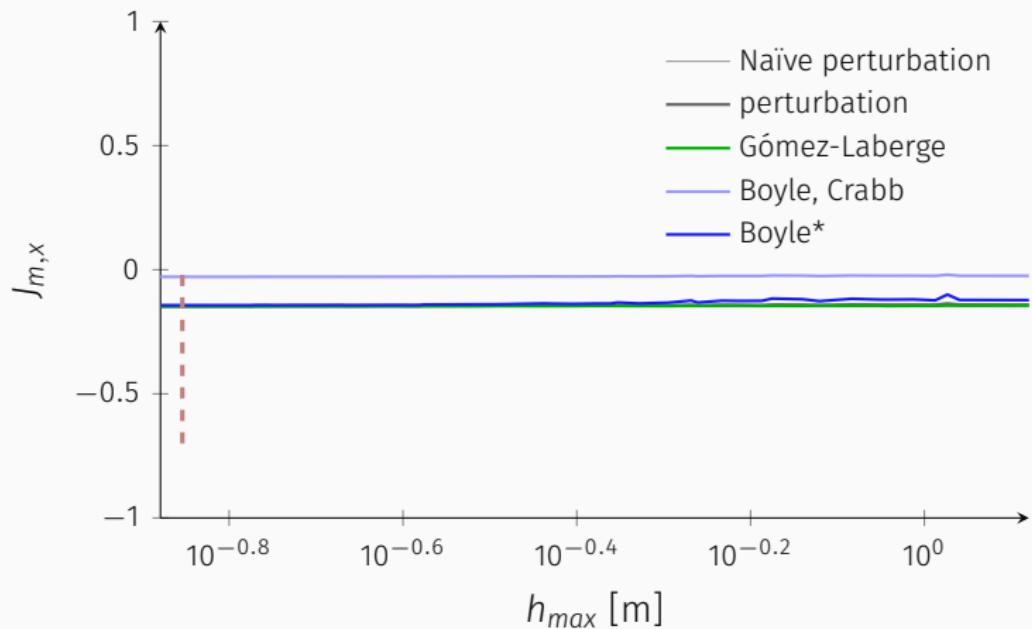


$h_{max} = 0.1$ m

$z_C = 0.02$ $\Omega \cdot \text{m}$

plot for s-

MESH DENSITY h_{max} FOR THE S- ELECTRODE



$d_{e\ell} = 0.2$ m

$z_C = 0.02$ $\Omega \cdot \text{m}$

plot for s-