GEOPHYSICAL APPLICATIONS OF ELECTRICAL IMPEDANCE TOMOGRAPHY Ph.D. Defence

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Derailment of 39 railway cars carrying crude oil Gogama, ON, Canada (2015)¹

Average 600 derailments per year, 74 with dangerous goods (Canada, 2008-2012)² Gogama clean-up costs will be "in the millions" – MPP F. Gelinas³

¹Transportation Safety Board of Canada, *Railway Investigation Report R15H0021*, Mar 2015

²Transportation Safety Board of Canada, Statistical Summary - Railway Occurrences 2013, Feb 2014

³M. Stackelberg, CBC News, Ontario bills CN \$350K for Gogama derailment clean-up, Dec 2015

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Mount Polley mine tailings spill, Likely, BC, Canada $(2014)^{\circ}$ spilled 4.5 mil. m³ of tailings with clean up costs of \$200–500 mil.

⁴CBC News, "Mount Polley mine tailings spill", Aug 2014

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Manage *slope stability* risks

a tool for real-time monitoring of slope movement

■ robust, reliable, informative reconstructions

Our tool of choice: Electrical Impedance Tomography Electrical Resistivity Tomography

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Manage *slope stability* risks

- a tool for real-time monitoring of slope movement electrode movement & resistivity
- robust, reliable, informative reconstructions algorithm, implementation, data

Our tool of choice: Electrical Impedance Tomography Electrical Resistivity Tomography

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Typical ERT Survey Equipment ABEM TerrameterLS⁵

⁵[http://www.ngi.no/upload/48876/TerrameterLS.jpg]

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⁶correct electrode wiring

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Long-term remote monitoring

Hollin Hill, UK⁷

⁷Automated Landslide Electrical Resistivity Tomography (ALERT) system

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Absolute imaging problem; large conductivity contrasts ... a Gauss-Newton nonlinear iterative solver

$$\min_{\mathbf{x}} ||\mathbf{A}\mathbf{x} - \mathbf{b}||_2^2 \tag{1}$$

$$\delta \mathbf{x}_n = -(\mathbf{J}_n^{\mathsf{T}} \mathbf{J}_n)^{-1} (\mathbf{J}_n^{\mathsf{T}} \mathbf{b})$$
(2)

$$\mathbf{x}_{n+1} = \mathbf{x}_n + \alpha_{n+1} \,\,\delta \mathbf{x}_{n+1} \tag{3}$$



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Absolute imaging problem; large conductivity contrasts ... a Gauss-Newton nonlinear iterative solver

$$\min_{\mathbf{x}} ||\mathbf{A}\mathbf{x} - \mathbf{b}||_{\mathbf{W}}^{2} + ||\lambda \mathbf{R}(\mathbf{x} - \mathbf{x}_{*})||_{2}^{2}$$
(1)

$$\mathbf{x}_{n+1} = -(\mathbf{y}_n \mathbf{v} \mathbf{y}_n + \lambda \mathbf{k} \mathbf{k}) \quad (\mathbf{y}_n \mathbf{v} \mathbf{y} - \lambda \mathbf{k} \mathbf{k} (\mathbf{x}_n - \mathbf{x}_*)) \quad (2)$$
$$\mathbf{x}_{n+1} = \mathbf{x}_n + \alpha_{n+1} \, \delta \mathbf{x}_{n+1} \tag{3}$$



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$$\delta \mathbf{x}_{n+1} = -(\mathbf{J}_n^{\mathsf{T}} \mathbf{W} \mathbf{J}_n + \lambda^2 \mathbf{R}^{\mathsf{T}} \mathbf{R})^{-1} (\mathbf{J}_n^{\mathsf{T}} \mathbf{W} \mathbf{b} - \lambda^2 \mathbf{R}^{\mathsf{T}} \mathbf{R} (\mathbf{x}_n - \mathbf{x}_*))$$



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This Work Addresses



Background material

- impedance imaging: fwd problem, hardware (CH2)
- rocks and conductivity: a review (CH3)
- inverse problems: composing algorithms (CH4)

This Work Addresses



Contributions; with geophysics applications

- problems with inverse problems: reliable algorithms (CH5)
- data quality and model mismatch: reliable data (CH6)
- electrode mvmt and modelling errors: reliable Jacobians (CH7)
- reconstructing surface movement: $[\mathbf{x}_{\sigma} \mathbf{x}_{m}]^{\mathsf{T}}$ (CH8)

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Thank You

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